

**44<sup>TH</sup> ASECAP STUDY & INFORMATION DAYS 2016** New ways of traffic incident detection

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## **Current conditions General Data**

#### The Slovenian motorway system

- 610 kilometers of motorways and expressways
- 21 tunnels in the Slovenian motorway system
- 20 km total length of the tunnels
- 38 km total length of tunnel tubes

Traffic incident detection

- 800 video detection cameras in tunnels
- 100 video detection cameras on open road
- 200 microwave detectors





# **Identification of problems**



- detection of incidents in poor visibility (fog, night, snow storms, smoke in tunnel)
- false alarms (driving in the wrong direction, light effects)
- detector reliability (in some situations alarm is not activated)
- unequipped areas of the motorway for detecting the incidents.



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## **Pilot projects**



### Three pilot projects for detecting incidents:

- detection of incidents in a tunnel with radar detection
- detection of incidents on open road with thermal vision cameras
- detection of vehicles driving in the wrong direction with inductive loops







## **Radar detection**

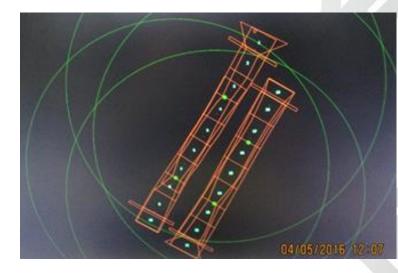


### The main problem:

- high number of false alarms (at entry and exit zones of the tunnel)
- non-functionality of detection in smoke circumstances

### We have implemented a simulation of the following incidents:

- stopped vehicle
- slow vehicle
- vehicle driving in the wrong direction
- pedestrians
- congestion
- object on the carriageway



### **Radar detection**



The advantages of the radar system:

- distance of up to 500 meters in each direction
- 360 degree radar detection area (180 degrees in tunnels)
- it operates in all situations, including fog, smoke or dust
- not sensitive to light effects or solar illumination on tunnel portals,
- the testing showed an extremely low number of false alarms,
- reliable detection of objects, including pedestrians
- minor sensitivity to dirt
- there is less chance of shifting of the detection zones,
- the life cycle of a radar detector is 20 years

## **Thermal camera**

#### The detection of traffic incidents is even more difficult on an open road

- visual and weather conditions are not constant;
- false alarms (driving in the wrong direction)

### The test system encompassed:

- thermal vision cameras,
- optical converters for image and data transfer
- servers with installed application



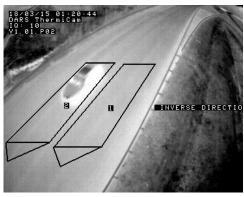




### **Thermal camera**



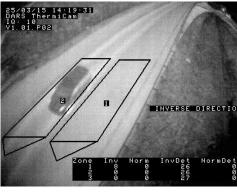
#### In the testing period, the camera operated in all weather conditions



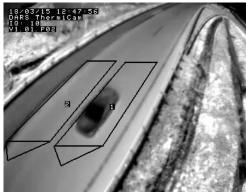
night



SNOW



rain



### **Thermal camera**



Based on testing results, we established that the thermal vision camera is suitable for video detection on an open road:

- light and weather conditions do not impact system operation
- there were no false events or system errors reported in the test period.
- all vehicles driving in the wrong direction were detected.



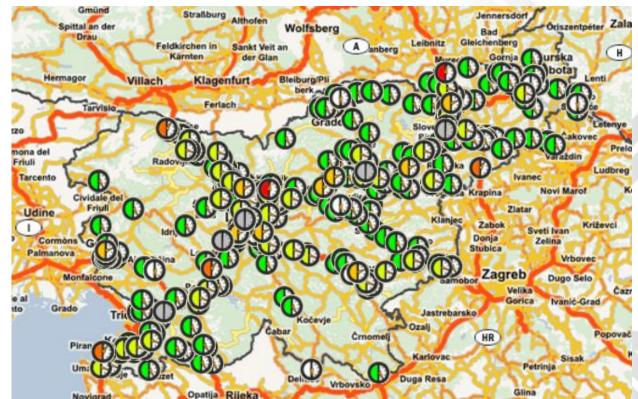
## **Inductive loop**



### **Current conditions:**

- traffic counters (no incident detected)
- 250 detected points
- connected to TMC

- 100 WWD/year
- 25% detected



## **Inductive loop**



### **Pilot project:**

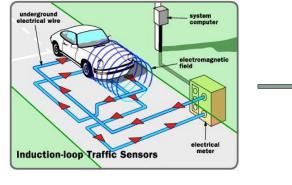
- 20 detected points
- application for detection driving in the wrong direction
- send this information to the DARS information system
- forwarded in real time to the participants in traffic



### APP (DarsTraffic+)



MAP-promet.si

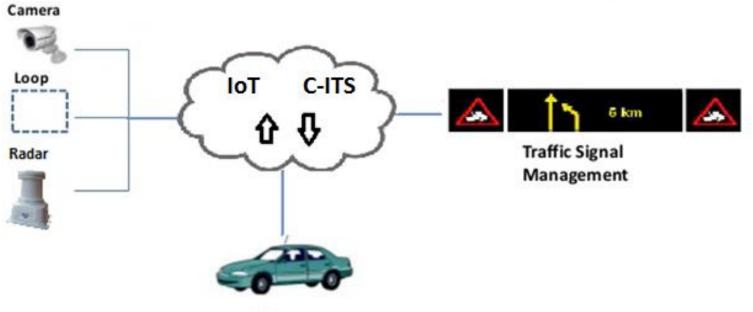




DARS MAP-kažipot.si

### Conclusion





Car

### THANK YOU FOR YOUR ATTENTION!